Front Propagation through a Perforated Wall

> Hiroshi Matano (Meiji University)

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## Outline

- 1. Introduction
- 2. Formulation of the problem
- 3. Propagation/blocking dichotomy
- 4. Sufficient conditions for **blocking**
- 5. Sufficient conditions for propagation

# 1. Introduction

Joint work with Henri Berestycki (EHESS) François Hamel (Aix-Marseille)





## **Bistable RD equation**

$$\frac{\partial u}{\partial t} = \Delta u + f(u) \quad \text{on } \mathbb{R}^N$$

 $f(0) = f(\alpha) = f(1) = 0, \quad f'(0) < 0, \ f'(1) < 0$ 

Existence of traveling wave

$$\frac{f(u)}{0} \qquad 1 \qquad u$$

f(u): bistable

$$\int_0^1 f(s)ds > 0$$

unbalanced

**1D** 
$$u_t = u_{xx} + f(u)$$
  $u(x,t) = \phi(x - ct), \ c > 0$ 



: TW profile

Fife & McLeod (ARMA1977)

potential  

$$W(u) = -\int_{0}^{u} f(s) ds$$

$$u$$

$$u$$
unequal well-depth



Description of the obstacle

Obstacle (wall)

 $K \subset \{x \in \mathbb{R}^N \mid 0 \le x_1 \le M\}$ 

finite thickness

 $\Omega := \mathbb{R}^N \setminus K \text{ connected } \partial \Omega \text{ smooth}$ 

For some results we also assume periodicity

$$\mathbf{P}_{2}, \dots \mathbf{P}_{N} \in \mathbb{R}_{y}^{N-1}$$
 (linearly independent)  
s.t.  $K + \mathbf{p}_{i} = K$   $(i = 2, \dots, N)$ 







Under what conditions can the front pass through the wall?



Some numerical simulations

Wall with wider holes



Simulation by Steffen Plunder (Kyoto University)

#### Wall with narrower holes



PropagationBlockingThe front has surface energy.surface tension





## More rigorous approach: sharp-interface limit



## 2. Formulation of the problem

### Planar-front like solution

$$(E) \begin{cases} u_t = \Delta u + f(u), & x \in \Omega := \mathbb{R}^N \setminus K \\ \frac{\partial u}{\partial \nu} = 0, & x \in \partial \Omega. \end{cases}$$
 Is there a planar-front like solution that approaches the obstacle K ?

**Theorem 1.** Assume  $K \subset \{x \in \mathbb{R}^N \mid x_1 \ge 0\}$ , There exists a <u>unique</u> entire solution  $\bar{u}$  of (E) satisfying  $0 < \bar{u} < 1$  ( $x \in \overline{\Omega}, t \in \mathbb{R}$ ) and  $\lim_{t \to -\infty} \sup_{x \in \Omega} |\bar{u}(t, x) - \phi(x_1 - ct)| = 0.$ This solution satisfies  $\bar{u}_t > 0$  for all  $x \in \overline{\Omega}, t \in \mathbb{R}$ .

Since  $\bar{u}$  is monotone in t, the following limit exists.

$$\bar{v}(x) := \lim_{t \to +\infty} \bar{u}(t, x) \quad (\text{limit profile})$$

$$\begin{cases} \Delta v + f(v) = 0, \quad x \in \Omega := \mathbb{R}^N \setminus K \\ \frac{\partial v}{\partial \nu} = 0, \quad x \in \partial \Omega. \end{cases}$$



### Limit profile



Q

Find conditions for propagation and those for blocking.

Dichotomy theorem

The limit profile converges either to 1 or to 0, uniformly regardlessof the choice of K.Method: Liouville type lemma

The family of <u>blocking walls form a closed set</u>, while that of non-blocking walls form an open set.

Sufficient conditions for blocking.

Blocking occurs if the holes are narrow enough.

Method: variational arguments

Sufficient conditions for propagation.

- (a) Wall with large holes;
- (b) Small capacity wall;
- (c) Parallel blade wall.

## 3. Propagation / blocking dichotomy

Classification of solution behaviors beyond the wall.



## Propagation / blocking dichotomy

**Theorem 2** (Dichotomy). One of the following alternatives holds:  $\lim_{x_1 \to +\infty} \bar{v}(x_1, y) = 1 \quad (\text{propagation}), \quad \lim_{x_1 \to +\infty} \bar{v}(x_1, y) = 0 \quad (\text{blocking})$ The above convergence is uniform with respect to  $y \in \mathbb{R}^{N-1}$  and K so long as  $K \subset \{x \in \mathbb{R}^N \mid 0 \leq x_1 \leq M\}.$ 

In particular, there is no blocking profile that converges to 0 too slowly.



### Liouville type lemma

[Y. Liu, K. Wang, J. Wei, K. Wu: Proc. AMS, to appear]

**Lemma 1.1** (Liouville type lemma). Let  $g : \mathbb{R} \to \mathbb{R}$  be a  $C^2$  function whose zeros are all isolated, and let v(x) be a bounded solution of

$$\Delta v + g(v) = 0 \quad in \ \mathbb{R}^N$$

that is <u>stable</u>. Assume that the one-dimensional equation w'' + g(w) = 0does not have a nonconstant stable solution. Then v is a constant.

### Definition of "stability"

$$\begin{cases} -\Delta \phi - g'(v)\phi = \lambda_R \phi, \ \phi > 0 & \text{in } B_R, \\ \phi = 0 & \text{on } \partial B_R \end{cases}$$

 $\lambda_R \ge 0$  for all R > 0.

Corollary 4. Let v be a bounded solution of  $\Delta v + f(v) = 0$  in  $\mathbb{R}^N$ that is stable. Then either v = 0 or v = 1.

#### Outline of the proof of Theorem 2

Suppose that there exists a sequence of walls  $K_j$  (j = 1, 2, 3, ...) such that the limit profiles  $v_j$  for  $K_j$  do not converge to 1 nor 0 fast enough.



By shifting  $v_j$  and taking the limit, we obtain a function  $v_{\infty}$  on  $\mathbb{R}^N$  s.t.  $0 < v_{\infty}(x) < 1$  on  $\mathbb{R}^N$ ,  $v_{\infty}$  is stable.

But this contradicts the Liouville type lemma.

#### Remark

Stability is preserved by spatial shifts and by limiting procedures.

## Propagation / blocking dichotomy

**Theorem 2** (Dichotomy). One of the following alternatives holds:  $\lim_{x_1 \to +\infty} \bar{v}(x_1, y) = 1 \quad (\text{propagation}), \quad \lim_{x_1 \to +\infty} \bar{v}(x_1, y) = 0 \quad (\text{blocking})$ The above convergence is uniform with respect to  $y \in \mathbb{R}^{N-1}$  and K so long as  $K \subset \{x \in \mathbb{R}^N \mid 0 \le x_1 \le M\}.$ 

Corollary 3. Let  $K_1, K_2, K_3, \ldots$  be a sequence of walls satisfying  $K_j \subset \{x \in \mathbb{R}^N \mid 0 \le x_1 \le M\} \quad (j = 1, 2, 3, \ldots)$ 

and converging to a wall  $K_{\infty}$  in the Hausdorff distance. If blocking occurs for every  $K_j$  (j = 1, 2, 3, ...) then the same holds for  $K_{\infty}$ .

$$\bar{v}_j \ (j = 1, 2, 3, \ldots)$$
 limit profile of  $K_j$   $\bar{v}_j \to \bar{v}_\infty$   
 $\downarrow$   $\lim_{x_1 \to +\infty} \bar{v}_\infty(x_1, y) = 0$ 

# 4. Conditions for blocking

Geometric obstruction

<u>Theorem 5.</u> Assume either of the following:
(K1) *K* is <u>periodic in *y*</u>.
(K2) The holes are <u>localized</u> in a bounded region.

If the holes are too small, then blocking occurs.



<u>Theorem 5.</u> Assume either of the following:

(K1) K is periodic in y.

(K2) The holes are <u>localized</u> in a bounded region.

If the holes are too small, then blocking occurs.

### <u>Remark</u>

- The assumptions (K1) and (K2) allow us to define an energy functional around the holes. The problem is open without these conditions.
- Whether blocking occurs or not does not simply depend on the size of the holes. As shown in [BBC 2016], blocking occurs if the opening angle is large, but not if the opening angle is small.



<u>Theorem 5.</u> Assume either of the following:

(K1) K is <u>periodic in y</u>.

(K2) The holes are <u>localized</u> in a bounded region.

If the holes are too small, then blocking occurs.

One-way blocking

(A) Narrow exit and <u>large</u> opening angles



(B) Narrow entrance but wide exit, and <u>small opening angles</u>.



## 5. Sufficient conditions for propagation

Three types of walls

Walls that allow propagation

(a) Wall with large holes

A ball of a critical radius  $R_0$  can pass through one of the holes, where  $R_0$  is to be specified later.

(b) Small capacity wall

*K* is <u>close to</u> a set of capacity 0 in Hausdorff distance.

( $K_{\varepsilon}$  is in the  $\varepsilon$  neighborhood of a zero capacity set  $K_0$ .)

(c) Parallel-blade wall

*K* consists of thin panels parallel to the  $x_1$  axis. More precisely,  $K_0$  is a locally finite union of hypersurfaces parallel to the  $x_1$  axis and let  $K_{\varepsilon}$ converge to  $K_0$  in a certain sense.



Walls that allow propagation

(a) Wall with large holes

A ball of a critical radius  $R_0$  can pass through one of the holes, where  $R_0$  is to be specified later. <u>Method</u>: comparison principle and sweeping argument

(b) Small capacity wall

*K* is <u>close to</u> a set of capacity 0 in Hausdorff distance.

<u>Method</u>: limiting argument, removal singularity, and dichotomy theorem (Cor.2).

(c) Parallel-blade wall

K consists of thin panels parallel to the  $x_1$  axis.

Method: sweeping method by "<u>quasi-subsolutions</u>" and relative Poincaré inequality



## 1. Wall with large holes

<u>Theorem 6.</u> If a ball of radius  $R_0$  can pass through one of the holes of the wall without touching K, then propagation occurs.

Let  $\Psi(x) \ge 0$  be a compactly supported radial subsolution:

$$\Delta \Psi + f(\Psi) = 0 \ (|x| < R_0), \ \Psi(x) = 0 \ (|x| \ge R_0)$$

satisfying  $\alpha < \Psi(0) = \max \Psi < 1$  (Aronson-Weinberger '78).



Strong maximum principle + sweeping argument Move the position of P continuously without hitting *K* 

## 2. Small capacity wall

**Theorem 7** (Small-capacity wall). Let  $K^{\varepsilon}$  ( $0 < \varepsilon \leq \varepsilon_0$ ) be a family of walls that is periodic in  $y \in \mathbb{R}^{N-1}$  and satisfies  $K^{\varepsilon} \subset \{x \in \mathbb{R}^N \mid 0 \leq x_1 \leq M\}, \quad \limsup_{\varepsilon \to 0} K^{\varepsilon} \subset K_0 \cup K_1,$ where  $K_0$  is a closed set of capacity 0,  $K_1$  is a wall with large holes or  $K_1 = \emptyset$ . Then for all sufficiently small  $\varepsilon > 0$ , propagation occurs for  $K^{\varepsilon}$ .



(a) Wall with a large hole.

(b) Wall with a large hole that is filled with debris of small capacity.

## 2. Small capacity wall

**Theorem 7** (Small-capacity wall). Let  $K^{\varepsilon}$  ( $0 < \varepsilon \leq \varepsilon_0$ ) be a family of walls that is periodic in  $y \in \mathbb{R}^{N-1}$  and satisfies  $K^{\varepsilon} \subset \{x \in \mathbb{R}^N \mid 0 \leq x_1 \leq M\}, \quad \limsup_{\varepsilon \to 0} K^{\varepsilon} \subset K_0 \cup K_1,$ where  $K_0$  is a closed set of capacity 0,  $K_1$  is a wall with large holes or  $K_1 = \emptyset$ . Then for all sufficiently small  $\varepsilon > 0$ , propagation occurs for  $K^{\varepsilon}$ .

### Sufficient conditions for capacity 0

- Hausdorff dimension of  $K_0 < N 2$ .
- (N-2) dimensional rectifiable manifold.

### Examples of $\underline{K}_0$

- Discrete set  $(N \ge 2) \rightarrow$  "Debris wall"
- Locally finite union of curves (N = 3) → "Filament wall"



## 2. Small capacity wall





Interpretation of the result

Since the front has positive thickness, it is not very sensitive to debris of small capacity.



## 3. Parallel-blade wall

is <u>periodic</u> in and consists of thin panels <u>parallel to</u> the  $x_1$  axis.

More precisely, lies in the neighborhood of which is an N-1 dimensional set parallel to  $\underline{x}_1$  axis.



$$\int_{\partial K^{\varepsilon} \cap \Delta_{\mathcal{P}}} |\nu \cdot \boldsymbol{e}_1| \, dS_x \leq \varepsilon_1$$

In 3D, a honeycomb wall is also an example.



Note:  $K_0$  has positive capacity as codim  $K_0 = 1$ 

## 3. Parallel-blade wall

is <u>periodic</u> in and consists of thin panels <u>parallel to</u> the  $x_1$  axis.

More precisely, lies in the neighborhood of which is an N-1 dimensional set parallel to  $\underline{x}_1$  axis.



**Theorem 8** (Parallel-blade wall). Let  $K^{\varepsilon}$   $(0 < \varepsilon \leq \varepsilon_0)$  be a family of  $\mathcal{P}$ -periodic parallel-blade walls converging to  $K_0 \subset [0, M] \times \Sigma$  as  $\varepsilon \to 0$ , Then for all sufficiently small  $\varepsilon > 0$ , propagation occurs for  $K^{\varepsilon}$ .

Method: sweeping method by "<u>quasi-subsolutions</u>" and relative Poincaré inequality **Theorem 8** (Parallel-blade wall). Let  $K^{\varepsilon}$   $(0 < \varepsilon \leq \varepsilon_0)$  be a family of  $\mathcal{P}$ -periodic parallel-blade walls converging to  $K_0 \subset [0, M] \times \Sigma$  as  $\varepsilon \to 0$ , Then for all sufficiently small  $\varepsilon > 0$ , propagation occurs for  $K^{\varepsilon}$ .

#### <u>Strategy of proof</u>: Sweeping argument by quasi-subsolutions.





## Relative Poincaré inequality

G. Buttazzo and B. Velichkov, *The spectral drop problem*, Contemporary Math. **666** (2016), pp. 111–135.

**Proposition 1.3.** Let  $\widehat{\Omega}$  be a domain in  $\mathbb{R}^N$  and let  $\eta_0$  be a real number with  $0 < \eta_0 < |\widehat{\Omega}|$ . Then there exists a constant C > 0 depending only on  $\widehat{\Omega}$  and  $\eta_0$  such that, for any open set  $D \subset \widehat{\Omega}$  satisfying  $|D| \leq \eta_0$  and any  $w \in H^1(\widehat{\Omega}) \cap C(\widehat{\Omega})$  such that w = 0 in  $\widehat{\Omega} \setminus D$ , the following holds:

$$\int_D |\nabla w|^2 dx \ge C |D|^{-\frac{2}{N}} \int_D w^2 dx.$$



## Summary:

We discussed whether or not a planar bistable front can propagate through a perforated wall.

1. <u>Classification of general behavior</u>:

Dichotomy theorem (via Liouville type lemma) Cor. the limit of blocking walls is again blocking.

- 2. <u>A sufficient condition for blocking</u>: (narrow holes)Method: construction of an upper barrier via a variational argument
- 3. <u>Three sufficient conditions for propagation</u>:

(a) large-hole walls (b) small-capacity walls (c) parallel-blade walls.

Method: (a) sweeping method, (b) removable singularity theory + dichotomy thm, (c) sweeping by <u>quasi-subsolutions</u>.

### **Open questions:**

1. <u>Tilted thin panels</u>: What if the panels are tilted ?



Proof of blocking for non-periodic walls
 Is there a way to apply variational arguments?

#### 3. <u>Homogenization problem</u>:

What if the size of the holes and the distance between adjacent holes both go to zero simultaneously?



Thank you!